

Optimal Experimental Designs for Process Robustness Studies



Ying Chen

(Research funded by a grant from GlaxoSmithKline Biologicals SA, Belgium)

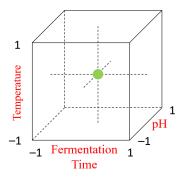
Supervisor: Prof. dr. Peter Goos (KU Leuven, University of Antwerp)

Co-supervisor: Dr. Bernard G. Francq (An employee of the GSK group of companies)

Overview

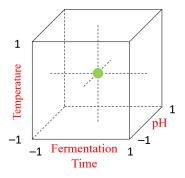
- Robust process
- Design selection criteria
- Design examples and evaluation
- Summary

• **Target operating condition**: a specific combination of settings of the process parameters



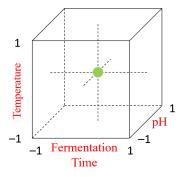


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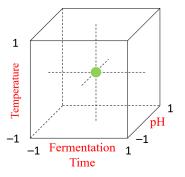
• Unavoidable deviations around the target condition during routine production

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- Are the responses very different from the response at the target operating condition? If not, the process is robust

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 \Rightarrow Precise prediction of the difference in responses is important

Design selection criteria

I-Optimality Criterion (Integrated Variance). I-optimal designs minimize the average prediction variance:

$$\frac{\int_{\chi} \mathbf{f}'(\mathbf{x}) \left(\mathbf{X}'\mathbf{X}\right)^{-1} \mathbf{f}(\mathbf{x}) d\mathbf{x}}{\int_{\chi} d\mathbf{x}}$$

- $\mathbf{x}' = [x_1, x_2, \dots, x_k]$: a point in the experimental region
- **f**(**x**): model expansion of **x**
- X: model matrix
- $\mathbf{f}'(\mathbf{x}) (\mathbf{X}'\mathbf{X})^{-1} \mathbf{f}(\mathbf{x})$: prediction variance at \mathbf{x} relative to σ_{ϵ}^2
- $\int_{\chi} d\mathbf{x}$: volume of the experimental region

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- $\int_{\chi} d\mathbf{x}$: volume of the experimental region
- M: moments matrix

Example moments matrix M: 3 quantitative factors

1	0	0	0	0	0	0	1/3	1/3	1/3
0	1/3	0	0	0	0	0	0	0	0
0	0	1/3	0	0	0	0	0	0	0
0	0	0	1/3	0	0	0	0	0	0
0	0	0	0	1/9	0	0	0	0	0
0	0	0	0	0	1/9	0	0	0	0
0	0	0	0	0	0	1/9	0	0	0
1/3	0	0	0	0	0	0	1/5	1/9	1/9
1/3	0	0	0	0	0	0	1/9	1/5	1/9
1/3	0	0	0	0	0	0	1/9	1/9	1/5

I_D-**Optimality Criterion** (Integrated Variance for Differences)

$$\frac{\int_{\chi} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{0})]' \left(\mathbf{X}'\mathbf{X}\right)^{-1} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{0})] d\mathbf{x}}{\int_{\chi} d\mathbf{x}}$$

• **0**: center of the experimental region, typically where the target operating condition is located

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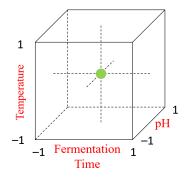
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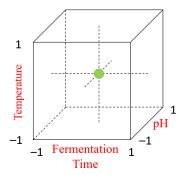
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Trinca, L., & Gilmour, S. (2015).Improved Split-Plot and Multi-Stratum Designs. <u>Technometrics</u>, <u>57</u>, 145–154. https://doi.org/10.1080/00401706.2014.915235





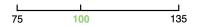
What if the target setting is not at the center?





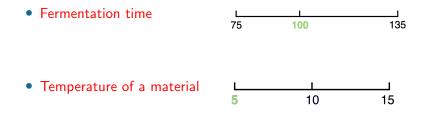
What if the target setting is *not* at the center?







What if the target setting is not at the center?





GI_D-**Optimality Criterion** (Generalized Integrated Variance for Differences)

$$\frac{\int_{\chi} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{t})]' \left(\mathbf{X}'\mathbf{X}\right)^{-1} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{t})] d\mathbf{x}}{\int_{\chi} d\mathbf{x}}$$

• t: target point



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- t: target point
- m: first column of M



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Three components:

- the average prediction variance
- the prediction variance at the target point
- average covariance between the predictions at each point in the experimental region and the prediction at the target point

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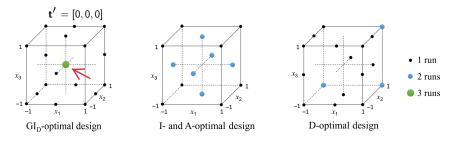
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Design examples

20-Run Designs for a Response Surface Model



- D-optimal designs maximize the determinant of the information matrix X'X
- A-optimal designs minimize the sum, or the average, of the diagonal elements of (X'X)⁻¹

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Design Evaluation

1. Relative $GI_{\rm D}$ -Efficiencies

 $\frac{GI_{\rm D}\text{-}\text{optimality criterion value of design 1}}{GI_{\rm D}\text{-}\text{optimality criterion value of design 2}}$



Design Evaluation

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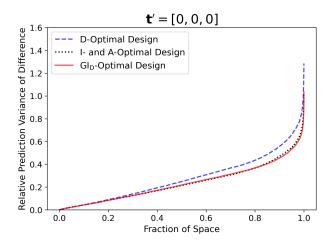
 $\frac{GI_{\rm D}\text{-}\text{optimality criterion value of design 1}}{GI_{\rm D}\text{-}\text{optimality criterion value of design 2}}$

Relative to the GI_D-optimal design:

- I- and A-Optimal Design: 99.64%
- D-optimal Design: 84.98%

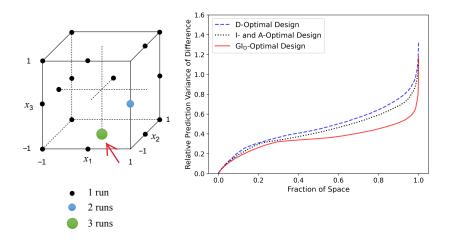


2. Difference Fraction of Design Space Plot



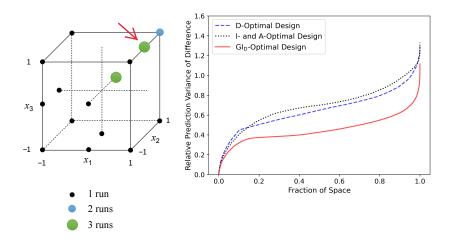
 $[\mathbf{f}(\mathbf{x}_i) - \mathbf{f}(\mathbf{t})]' (\mathbf{X}'\mathbf{X})^{-1} [\mathbf{f}(\mathbf{x}_i) - \mathbf{f}(\mathbf{t})].$ (de Oliveira et al., 2022)

$$t' = [0, 0, -1]$$



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$$\bm{t}' = [1,0,1]$$



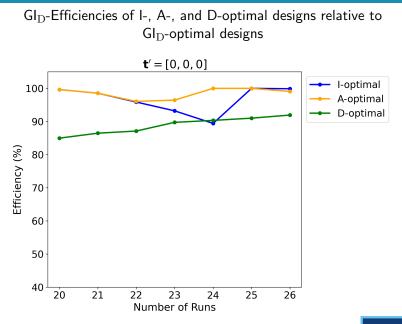
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 $\mathbf{t}' = [1,1,1]$

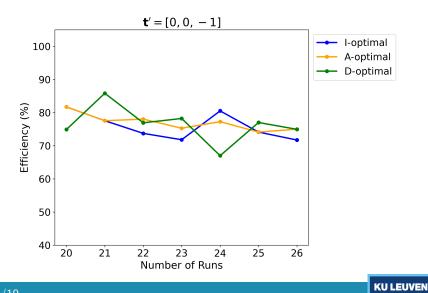
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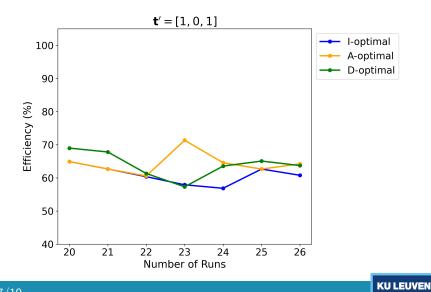


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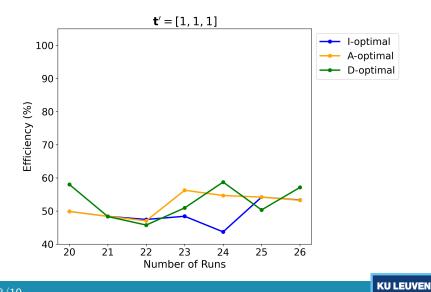
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Summary

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- Gl_D-optimal designs tend to allocate more runs to the target point

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- Gl_D-optimal designs minimize the average prediction variance of differences in responses, where the target point can be any point in the experimental region
- $\mathsf{Gl}_D\text{-}\mathsf{optimal}$ designs tend to allocate more runs to the target point
- ${\sf Gl}_D\text{-}{\sf optimal}$ designs outperform other designs for process robustness studies, especially when the target point is not at the center





Optimal Experimental Designs for Process Robustness Studies



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Supervisor: Prof. dr. Peter Goos (KU Leuven, University of Antwerp)

Co-supervisor: Dr. Bernard G. Francq (An employee of the GSK group of companies) Relative I-, A- and D-efficiencies of the GI_D -optimal designs ($\mathbf{t}' = [0, 0, 0]$) for estimating a response surface model in three quantitative factors

	Design Evaluation Criterion						
Run Size	l	А	D				
20	92.00%	92.32%	94.47%				
21	94.10%	95.26%	93.21%				
22	90.36%	95.68%	97.64%				
23	93.17%	99.12%	98.46%				
24	98.69%	100%	96.39%				
25	100%	100%	93.94%				
26	97.22%	98.08%	94.01%				
Average	95.08%	97.21%	95.45%				