

# Optimal Experimental Designs for Process Robustness Studies



#### **Ying Chen**

(Research funded by a grant from GlaxoSmithKline Biologicals SA, Belgium)

 **Supervisor: Prof. dr. Peter Goos** (KU Leuven, University of Antwerp)

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### **Overview**

- Robust process
- Design selection criteria
- Design examples and evaluation
- Summary

Target operating condition: a specific combination of settings of the process parameters



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 $\Rightarrow$  Precise prediction of the difference in responses is important

### Design selection criteria

I-Optimality Criterion (Integrated Variance). I-optimal designs minimize the average prediction variance:

$$
\frac{\int_{\chi} f'(x) (\mathbf{X}'\mathbf{X})^{-1} f(x) dx}{\int_{\chi} d\mathbf{x}}
$$

- $\mathbf{x}' = [x_1, x_2, \dots, x_k]$ : a point in the experimental region
- $f(x)$ : model expansion of x
- X: model matrix
- $f'(x) (X'X)^{-1} f(x)$ : prediction variance at x relative to  $\sigma_\epsilon^2$
- $\bullet \ \int_{\chi} d\textbf{x}$ : volume of the experimental region

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$$

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- $\bullet \ \int_{\chi} d\textbf{x}$ : volume of the experimental region
- **M**: moments matrix

#### Example moments matrix M: 3 quantitative factors



**ID-Optimality Criterion** (Integrated Variance for Differences)

$$
\frac{\int_{\chi} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{0})]' (\mathbf{X}'\mathbf{X})^{-1} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{0})] d\mathbf{x}}{\int_{\chi} d\mathbf{x}}
$$

• 0: center of the experimental region, typically where the target operating condition is located

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螶 Trinca, L., & Gilmour, S. (2015).Improved Split-Plot and Multi-Stratum Designs. Technometrics, 57, 145–154. <https://doi.org/10.1080/00401706.2014.915235>







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$$
\frac{\int_{\chi} [f(\mathbf{x}) - f(\mathbf{t})]' (\mathbf{X}'\mathbf{X})^{-1} [f(\mathbf{x}) - f(\mathbf{t})] d\mathbf{x}}{\int_{\chi} d\mathbf{x}}
$$

• t: target point



$$
\frac{\int_X [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{t})]' (\mathbf{X}'\mathbf{X})^{-1} [\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{t})] d\mathbf{x}}{\int_X d\mathbf{x}} =
$$
\n
$$
\text{tr}\left[ (\mathbf{X}'\mathbf{X})^{-1} \mathbf{M} \right] + \mathbf{f}'(\mathbf{t}) (\mathbf{X}'\mathbf{X})^{-1} \mathbf{f}(\mathbf{t}) - 2\mathbf{m}' (\mathbf{X}'\mathbf{X})^{-1} \mathbf{f}(\mathbf{t})
$$

- t: target point
- m: first column of M



$$
\frac{\int_X [f(\mathbf{x}) - f(\mathbf{t})]' (\mathbf{X}'\mathbf{X})^{-1} [f(\mathbf{x}) - f(\mathbf{t})] d\mathbf{x}}{\int_X d\mathbf{x}} =
$$
\n
$$
\text{tr}\left[ (\mathbf{X}'\mathbf{X})^{-1} \mathbf{M} \right] + f'(\mathbf{t}) (\mathbf{X}'\mathbf{X})^{-1} f(\mathbf{t}) - 2\mathbf{m}' (\mathbf{X}'\mathbf{X})^{-1} f(\mathbf{t})
$$

Three components:

- the average prediction variance
- the prediction variance at the target point
- average covariance between the predictions at each point in the experimental region and the prediction at the target point

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Three components:

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#### Design examples

#### 20-Run Designs for a Response Surface Model



- D-optimal designs maximize the determinant of the information matrix X′X
- A-optimal designs minimize the sum, or the average, of the diagonal elements of  $\left(\mathsf{X}'\mathsf{X}\right)^{-1}$

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## Design Evaluation

#### 1. Relative  $GI_{D}$ -Efficiencies

 $G<sub>D</sub>$ -optimality criterion value of design 1  $G<sub>D</sub>$ -optimality criterion value of design 2





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 $G<sub>D</sub>$ -optimality criterion value of design 1  $G<sub>D</sub>$ -optimality criterion value of design 2

Relative to the  $GI_D$ -optimal design:

- I- and A-Optimal Design: 99.64%
- D-optimal Design: 84.98%



#### 2. Difference Fraction of Design Space Plot



 $[\mathbf{f}(\mathbf{x}_i) - \mathbf{f}(\mathbf{t})]'(\mathbf{X}'\mathbf{X})^{-1}[\mathbf{f}(\mathbf{x}_i) - \mathbf{f}(\mathbf{t})]$ . (de Oliveira et al., 2022)



$$
\bm{t}'=[0,0,-1]
$$



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$$
\bm{t}'=[1,0,1]
$$



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1	2
$x_3$	1
1	2
2	3
3	4
4	5
5	12
6	12
7	1
8	10
9	20
10	20
11	20
12	20
13	20
14	20
15	20
16	20
17	22
18	20
19	20
10	0.0
11	22
21	22
22	20
22	0.4
22	0.4
22	0.4
22	0.8
22	0.8
22	0.8
22	0.8

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# Summary

•  $GI_D$ -optimal designs minimize the average prediction variance of differences in responses, where the target point can be any point in the experimental region



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- $GI<sub>D</sub>$ -optimal designs tend to allocate more runs to the target point



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- $GI<sub>D</sub>$ -optimal designs minimize the average prediction variance of differences in responses, where the target point can be any point in the experimental region
- $GI<sub>D</sub>$ -optimal designs tend to allocate more runs to the target point
- $GI<sub>D</sub>$ -optimal designs outperform other designs for process robustness studies, especially when the target point is not at the center





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Relative I-, A- and D-efficiencies of the GI $_{\rm D}$ -optimal designs  $(\mathbf{t}'=[0,0,0])$ for estimating a response surface model in three quantitative factors

